



Citation for published version:

Cozzi, M & Valdinoci, E 2020, 'On the growth of nonlocal catenoids', *Rendiconti Lincei. Matematica e Applicazioni*, vol. 31, no. 1, pp. 237-248. <https://doi.org/10.4171/RLM/888>

DOI:

[10.4171/RLM/888](https://doi.org/10.4171/RLM/888)

Publication date:

2020

Document Version

Peer reviewed version

[Link to publication](#)

(C) 2020 EMS Publishing House.

University of Bath

Alternative formats

If you require this document in an alternative format, please contact:
openaccess@bath.ac.uk

General rights

Copyright and moral rights for the publications made accessible in the public portal are retained by the authors and/or other copyright owners and it is a condition of accessing publications that users recognise and abide by the legal requirements associated with these rights.

Take down policy

If you believe that this document breaches copyright please contact us providing details, and we will remove access to the work immediately and investigate your claim.

ON THE GROWTH OF NONLOCAL CATENOIDS

MATTEO COZZI AND ENRICO VALDINOCI

ABSTRACT. As well known, classical catenoids in \mathbb{R}^3 possess logarithmic growth at infinity. In this note we prove that the case of nonlocal minimal surfaces is significantly different, and indeed all nonlocal catenoids must grow at least linearly. More generally, we prove that stationary sets for the nonlocal perimeter functional which grow sublinearly at infinity are necessarily half-spaces.

1. INTRODUCTION

The recent literature has taken into account a number of important problems related to energies of nonlocal type. One of the most challenging topics in this context is given by the so-called “nonlocal minimal surfaces”, as introduced by [10]. These objects are boundaries of sets that minimize a nonlocal perimeter functional, which takes into account all the interactions—weighted by a rotation and translation invariant homogeneous kernel with polynomial decay—between the points of a given set and the points of its complement.

More precisely, for $\alpha \in (0, 1)$, the kernel interaction between two disjoint measurable sets $E, F \subseteq \mathbb{R}^{n+1}$ is given by

$$I_\alpha(E, F) := \alpha(1 - \alpha) \iint_{E \times F} \frac{dx dy}{|x - y|^{n+1+\alpha}},$$

and the α -perimeter of E in a given domain Ω is defined as

$$\text{Per}_\alpha(E, \Omega) := I_\alpha(E \cap \Omega, \Omega \setminus E) + I_\alpha(E \cap \Omega, \mathbb{R}^{n+1} \setminus (E \cup \Omega)) + I_\alpha(E \setminus \Omega, \Omega \setminus E), \quad (1)$$

which takes into account all the interactions of the set E with its complement, where at least one of the two interacting points lies in the domain Ω .

The minimizers of (1) are often called α -minimal sets in Ω , and their boundaries nonlocal, or fractional, α -minimal surfaces in Ω .

If E is a minimizer of (1) in any given ball of \mathbb{R}^{n+1} , we say that E is an α -minimal set in \mathbb{R}^{n+1} .

We also consider here a notion of α -stationarity related to the fractional perimeter which is very general, and basically relies on a definition “in the viscosity sense” (in particular, the sets under consideration are only assumed to be measurable, and no smoothness or finite perimeter requirement is necessary in the framework that we adopt). Namely, we say that E is α -stationary in a domain Ω of \mathbb{R}^{n+1} if for every $x \in \partial E \cap \Omega$ the following conditions hold:

- **[Touching from the interior]** for any set F with C^2 boundary in a neighborhood of x such that $F \subseteq E$ and $x \in \partial E \cap \partial F$, we have that $H_\alpha[F](x) \geq 0$;
- **[Touching from the exterior]** for any set F with C^2 boundary in a neighborhood of x such that $F \supseteq E$ and $x \in \partial E \cap \partial F$, we have that $H_\alpha[F](x) \leq 0$.

Both authors are members of INdAM/GNAMPA. The first author was also a member of the Barcelona Graduate School of Mathematics. His research is supported by a Royal Society Newton International Fellowship and by the MINECO grants MDM-2014-0445, MTM2014-52402-C3-1-P, and MTM2017-84214-C2-1-P. The last author is supported by the Australian Research Council Discovery Project 170104880 NEW “Nonlocal Equations at Work”.

In the setting above, the notation $H_\alpha[F](x)$ stands for the nonlocal mean curvature at a point $x \in \partial F$, defined as

$$H_\alpha[F](x) = \text{P.V.} \int_{\mathbb{R}^{n+1}} \frac{\chi_{\mathbb{R}^{n+1} \setminus F}(y) - \chi_F(y)}{|x - y|^{n+1+\alpha}} dy,$$

where, as usual, ‘‘P.V.’’ denotes the Principal Value in the sense of Cauchy.

We also remark that if a set E is touched from the inside at $x \in \partial E$ by a C^2 set F , then the nonlocal mean curvature of E is well defined and belongs to $\mathbb{R} \cup \{-\infty\}$. Similarly, if a set E is touched from the outside at $x \in \partial E$ by a C^2 set F , then the nonlocal mean curvature of E is well defined in $\mathbb{R} \cup \{+\infty\}$. In particular, if E is α -stationary its nonlocal mean curvature is well defined and finite at points which can be touched from either inside or outside.

Notice that sets with C^2 boundary in a neighborhood of x for which $H_\alpha[F](x) = 0$ are α -stationary at x in the viscosity sense made precise above. Also, local minimizers of the α -perimeter are α -stationary (see [10, Theorem 5.1]).

Though the nonlocal perimeter recovers the classical perimeter, as well as the nonlocal minimal surfaces recover the classical minimal surfaces, up to normalizing constants and in an appropriate limit sense as $\alpha \nearrow 1$, see [2, 17, 1, 11], the nonlocal setting provides a number of extremely difficult problems and several striking differences with respect to the classical case. In particular, as $\alpha \searrow 0$, the functional in (1) is related to a convex combination of Lebesgue measures, with coefficients taking into account the behavior of the set at infinity, see [25, 20]. The lack of regularity properties for this limit functional, combined with the predominant effects of the energy contributions at infinity, produce serious difficulties in the development of the regularity theory in dimension higher than two and a series of new boundary stickiness effects, see [21, 3]. See also [16, 22] for recent reviews on these and on related topics.

One line of research related to nonlocal minimal surfaces consists in detecting nonlocal counterparts of classical objects, such as nonlocal catenoids, see [19], nonlocal helicoids, see [13], surfaces of constant nonlocal mean curvature, see [18, 6, 7, 8].

Interestingly, some of these nonlocal objects, such as the (double) helicoid, show exactly the same behavior of their classical counterparts, and others, such as the surfaces with constant nonlocal curvature, can be obtained by using delicate bifurcation methods from the corresponding classical surfaces. On the other hand, some other nonlocal surfaces, such as the nonlocal catenoids, exhibit important structural differences with respect to their classical analogues. As a matter of fact (see Figure 1 on page 115 of [19]) the nonlocal catenoid constructed in Theorem 1 of [19] can be seen as the boundary of an α -stationary set which possesses linear growth at infinity. More precisely, such a two-dimensional surface can be described for large $r := \sqrt{x_1^2 + x_2^2}$ as a two-leaves graph of the form $|x_3| = \varphi(r)$, with

$$\lim_{r \rightarrow +\infty} \frac{\varphi(r)}{r} = c\sqrt{1 - \alpha}, \quad (2)$$

for some $c > 0$.

We stress that (2) reveals an important structural difference with respect to the local case, since the classical catenoid possesses logarithmic, rather than linear, growth at infinity. Therefore, a natural question arising from these considerations is whether or not one can construct nontrivial α -stationary sets with sublinear growth at infinity.

The main result of this paper is that the answer to this question is negative, namely a sublinear growth at infinity necessarily imposes that the α -stationary set is a half-space

(differently from what happens in the local case). More precisely, we prove the following result:

Theorem 1. *Let $n \geq 1$ be an integer and $\alpha \in (0, 1)$. If E is an α -stationary set in \mathbb{R}^{n+1} satisfying*

$$\partial E \subseteq \left\{ x = (x', x_{n+1}) \in \mathbb{R}^{n+1} : |x_{n+1}| < \varphi(|x'|) \right\}, \quad (3)$$

for some continuous function $\varphi : [0, +\infty) \rightarrow (0, +\infty)$ such that

$$\lim_{r \rightarrow +\infty} \frac{\varphi(r)}{r} = 0, \quad (4)$$

then E is a half-space.

To appreciate the optimality of the sublinear condition in Theorem 1, one can compare (4) with (2).

Notice that, when ∂E is also assumed to be a graph over the whole horizontal hyperplane, stronger results are available. In [5, Theorem 1.6], the flatness of ∂E is deduced allowing φ to have linear growth at infinity, with any slope. Subsequently, this result has been improved in [15, Theorem 1.3], requiring only a one-sided bound on ∂E —i.e., that only one of the inclusions of the forthcoming (6) is satisfied, with φ linear at infinity. See also [24, 23], and again [15] for related rigidity results of Bernstein and Moser type.

2. PROOF OF THEOREM 1

In light of assumption (3), only two situations are possible, up to exchanging E with its complement: either ∂E is of *catenoid-type*, meaning that

$$E \subseteq \left\{ x \in \mathbb{R}^{n+1} : |x_{n+1}| < \varphi(|x'|) \right\}, \quad (5)$$

or ∂E is of *graph-type*, i.e., it holds

$$\left\{ x \in \mathbb{R}^{n+1} : x_{n+1} < -\varphi(|x'|) \right\} \subseteq E \subseteq \left\{ x \in \mathbb{R}^{n+1} : x_{n+1} < \varphi(|x'|) \right\}. \quad (6)$$

We deal with these two cases separately, each in one of the two subsequences that compose the remainder of the present section. More specifically, Theorem 1 will be a consequence of the combination of the forthcoming Theorems 2 and 5.

2.1. Catenoid-type α -stationary surfaces. Here, we prove Theorem 1 under the assumption that (5) holds true. More precisely, we establish the following result.

Theorem 2. *There exists no nontrivial α -stationary set E in \mathbb{R}^{n+1} such that (5) holds true for some continuous function $\varphi : [0, +\infty) \rightarrow (0, +\infty)$ satisfying (4).*

Theorem 2 is proved via a touching argument based on the maximum principle for α -stationary sets, used with the barrier constructed in the next proposition.

Proposition 3. *There exists a small $\varepsilon_0 > 0$ such that, for every $\varepsilon \in (0, \varepsilon_0]$, there exists a set F_ε of the form*

$$F_\varepsilon := \left\{ x \in \mathbb{R}^{n+1} : |x_{n+1}| < v_\varepsilon(x') \right\}, \quad (7)$$

for some smooth, radially non-decreasing function $v_\varepsilon : \mathbb{R}^n \rightarrow [\varepsilon, +\infty)$ satisfying

$$\begin{cases} v_\varepsilon(x') = \varepsilon & \text{for } x' \in B'_1 \\ \varepsilon \leq v_\varepsilon(x') \leq \varepsilon|x'| & \text{for } x' \in B'_2 \setminus B'_1 \\ v_\varepsilon(x') = \varepsilon|x'| & \text{for } x' \in \mathbb{R}^n \setminus B'_2, \end{cases} \quad (8)$$

and $v_\varepsilon \leq v_{\varepsilon'}$ in \mathbb{R}^n for every $0 < \varepsilon \leq \varepsilon' \leq \varepsilon_0$, such that

$$H_\alpha[F_\varepsilon](x) > 0 \quad \text{for every } x \in \partial F_\varepsilon. \quad (9)$$

Remark 4. Proposition 3 reveals a structural difference between the classical and the nonlocal cases: for instance, in dimension 2, the (mean) curvature of the set F_ε necessarily vanishes at points $(x', x_2) \in \partial F_\varepsilon$ with $x' \in \mathbb{R} \setminus (-2, 2)$, and so the analogue of (9) cannot hold in the classical case. In higher dimensions this difference is even more contrasting, as the standard mean curvature of F_ε is actually negative at these points. For other barriers of purely nonlocal character see also Proposition 7.3 in [21], Proposition 5 in [14], and Proposition 3.1 and Lemma 8.1 in [12].

Proof of Proposition 3. Let $\eta \in C_c^\infty(\mathbb{R}^n)$ be a radially non-increasing cut-off function satisfying $\eta = 1$ in B'_1 and $\eta = 0$ in $\mathbb{R}^n \setminus B'_2$. We define

$$v(x') := \eta(x') + (1 - \eta(x'))|x'|$$

and, given $\varepsilon > 0$,

$$v_\varepsilon(x') := \varepsilon v(x'),$$

for every $x' \in \mathbb{R}^n$. It is immediate to check that v_ε is a smooth, radially non-decreasing function verifying (8) and

$$\|\nabla v_\varepsilon\|_{L^\infty(\mathbb{R}^n)} + \|D^2 v_\varepsilon\|_{L^\infty(\mathbb{R}^n)} \leq C\varepsilon, \quad (10)$$

for some dimensional constant $C > 0$. We claim that the set F_ε defined by (7) satisfies (9).

Let \mathcal{C}_ε be the cone given by

$$\mathcal{C}_\varepsilon := \left\{ x \in \mathbb{R}^{n+1} : -\varepsilon|x'| < x_{n+1} < \varepsilon|x'| \right\}.$$

In [19, Section 10], it is proved that

$$H_\alpha[\mathcal{C}_\varepsilon](x) = \frac{M(\varepsilon)}{|x|^\alpha} \quad \text{for every } x \in \partial\mathcal{C}_\varepsilon \setminus \{0\}, \quad (11)$$

for some continuous function $M : (0, +\infty) \rightarrow \mathbb{R}$ such that

$$\lim_{\varepsilon \rightarrow 0^+} M(\varepsilon) = +\infty. \quad (12)$$

In particular, there exists $\bar{\varepsilon} \in (0, 1/2)$ such that $M(\varepsilon) > 0$ for every $\varepsilon \in (0, \bar{\varepsilon})$. In the following, we will always assume ε to lie in such interval.

Let $x \in \partial F_\varepsilon \setminus B_4$. Since $F_\varepsilon \setminus B_3 = \mathcal{C}_\varepsilon \setminus B_3$, we have that $x \in \partial\mathcal{C}_\varepsilon$ and

$$\begin{aligned} |H_\alpha[F_\varepsilon](x) - H_\alpha[\mathcal{C}_\varepsilon](x)| &= \left| \int_{B_3} \frac{\chi_{\mathbb{R}^{n+1} \setminus F_\varepsilon}(y) - \chi_{F_\varepsilon}(y) - \chi_{\mathbb{R}^{n+1} \setminus \mathcal{C}_\varepsilon}(y) + \chi_{\mathcal{C}_\varepsilon}(y)}{|x-y|^{n+1+\alpha}} dy \right| \\ &\leq 2 \int_{B_3} \frac{dy}{|x-y|^{n+1+\alpha}} \leq \frac{4^{n+2+\alpha}|B_3|}{|x|^{n+1+\alpha}} \leq \frac{C}{|x|^\alpha}. \end{aligned}$$

From now on, C will indicate a constant larger than 1 that depends only on n and α , and whose value may possibly change from line to line. By the above estimate and (11), we deduce that

$$H_\alpha[F_\varepsilon](x) \geq H_\alpha[\mathcal{C}_\varepsilon](x) - |H_\alpha[F_\varepsilon](x) - H_\alpha[\mathcal{C}_\varepsilon](x)| \geq \frac{M(\varepsilon) - C}{|x|^\alpha}.$$

Hence, thanks to (12), there exists $\varepsilon_1 \in (0, 1)$ such that

$$H_\alpha[F_\varepsilon](x) > 0 \quad \text{for every } x \in \partial F_\varepsilon \setminus B_4, \quad (13)$$

provided $\varepsilon \in (0, \varepsilon_1]$.

We now deal with the case $x \in \partial F_\varepsilon \cap B_4$. Let $x' \in B'_4$. Without loss of generality, we may assume that $x_{n+1} > 0$, i.e., that $x_{n+1} = v_\varepsilon(x')$. Through computations analogous to those made in [6, Lemma 4.1] for $n = 1$, we write the α -mean curvature of F_ε at x as

$$H_\alpha[F_\varepsilon](x) = 2 \text{P.V.} \int_{\mathbb{R}^n} G\left(\frac{v_\varepsilon(x') - v_\varepsilon(y')}{|x' - y'|}\right) \frac{dy'}{|x' - y'|^{n+\alpha}} \\ + 2 \int_{\mathbb{R}^n} \left\{ G(+\infty) - G\left(\frac{v_\varepsilon(x') + v_\varepsilon(y')}{|x' - y'|}\right) \right\} \frac{dy'}{|x' - y'|^{n+\alpha}},$$

with

$$G(t) = \int_0^t \frac{d\tau}{(1 + \tau^2)^{\frac{n+1+\alpha}{2}}} \quad \text{for } t \in \mathbb{R}.$$

Observe that G is an odd, increasing functions that satisfies $G(0) = 0$ and

$$|G(t_1) - G(t_2)| \leq |t_1 - t_2| \quad \text{for every } t_1, t_2 \in \mathbb{R}. \quad (14)$$

To estimate the integrals above, we distinguish between the two cases $y' \in B'_\varepsilon(x')$ and $y' \in \mathbb{R}^n \setminus B'_\varepsilon(x')$. In the former case, thanks to (14) and (10) we have

$$\left| \text{P.V.} \int_{B_\varepsilon(x')} G\left(\frac{v_\varepsilon(x') - v_\varepsilon(y')}{|x' - y'|}\right) \frac{dy'}{|x' - y'|^{n+\alpha}} \right| \\ = \left| \int_{B_\varepsilon(x')} \left\{ G\left(\frac{v_\varepsilon(x') - v_\varepsilon(y')}{|x' - y'|}\right) - G\left(\frac{\nabla v_\varepsilon(x') \cdot (x' - y')}{|x' - y'|}\right) \right\} \frac{dy'}{|x' - y'|^{n+\alpha}} \right| \quad (15) \\ \leq \int_{B_\varepsilon(x')} \frac{|v_\varepsilon(x') - v_\varepsilon(y') - \nabla v_\varepsilon(x') \cdot (x' - y')|}{|x' - y'|^{n+1+\alpha}} dy' \leq C\varepsilon \int_{B_\varepsilon} \frac{dz'}{|z'|^{n-1+\alpha}} \\ \leq C\varepsilon^{2-\alpha}.$$

Also, from (8) it easily follows that, for all $y' \in B_\varepsilon(x')$,

$$G(+\infty) - G\left(\frac{v_\varepsilon(x') + v_\varepsilon(y')}{|x' - y'|}\right) = \int_{\frac{v_\varepsilon(x') + v_\varepsilon(y')}{|x' - y'|}}^{+\infty} \frac{d\tau}{(1 + \tau^2)^{\frac{n+1+\alpha}{2}}} \\ \geq 2^{-\frac{n+1+\alpha}{2}} \int_{\frac{10\varepsilon}{|x' - y'|}}^{+\infty} \frac{d\tau}{\tau^{n+1+\alpha}} \geq \frac{C^{-1}}{\varepsilon^{n+\alpha}} |x' - y'|^{n+\alpha},$$

and thus

$$\int_{B'_\varepsilon(x')} \left\{ G(+\infty) - G\left(\frac{v_\varepsilon(x') + v_\varepsilon(y')}{|x' - y'|}\right) \right\} \frac{dy'}{|x' - y'|^{n+\alpha}} \geq \frac{C^{-1}}{\varepsilon^\alpha}. \quad (16)$$

On the other hand, using again (10), (14), and the monotonicity of G , we find that

$$\int_{\mathbb{R}^n \setminus B_\varepsilon(x')} \left\{ G\left(\frac{v_\varepsilon(x') - v_\varepsilon(y')}{|x' - y'|}\right) + G(+\infty) - G\left(\frac{v_\varepsilon(x') + v_\varepsilon(y')}{|x' - y'|}\right) \right\} \frac{dy'}{|x' - y'|^{n+\alpha}} \\ \geq \int_{\mathbb{R}^n \setminus B_\varepsilon(x')} \frac{-G(\|\nabla v_\varepsilon\|_{L^\infty(\mathbb{R}^n)}) + 0}{|x' - y'|^{n+\alpha}} dy' \geq -G(C\varepsilon) \int_{\mathbb{R}^n \setminus B_\varepsilon} \frac{dz'}{|z'|^{n+\alpha}} \geq -C\varepsilon^{1-\alpha}.$$

By putting together the last estimate with (15) and (16), we conclude that

$$H_\alpha[F_\varepsilon](x) \geq \frac{2}{\varepsilon^\alpha} (C^{-1} - C\varepsilon - C\varepsilon^2) \quad \text{for every } x \in \partial F_\varepsilon \cap B_4.$$

In particular, there exists $\varepsilon_2 \in (0, 1)$ such that

$$H_\alpha[F_\varepsilon](x) > 0 \quad \text{for every } x \in \partial F_\varepsilon \cap B_4,$$

provided $\varepsilon \in (0, \varepsilon_2]$. The combination of this and (13) gives (9). \square

With the result of Proposition 3 in hand, we are now ready to proceed with the proof of Theorem 2.

Proof of Theorem 2. We argue by contradiction and suppose that such an α -stationary set exists. Thanks to the properties of φ and hypothesis (5), for every $\delta > 0$, there exists a constant $C_\delta > 0$ such that

$$E \subseteq \left\{ x \in \mathbb{R}^{n+1} : |x_{n+1}| < C_\delta + \delta|x'| \right\}, \quad (17)$$

Let now $\varepsilon_0 > 0$ be the parameter found in Proposition 3 and choose $\delta := \varepsilon_0/8$. We then consider the rescaled set $E_\star := \lambda E$, with $\lambda := \varepsilon_0/(8C_{\varepsilon_0/8})$. Of course, E_\star is α -stationary. Moreover, thanks to (5) and (17), it satisfies

$$E_\star \subseteq \left\{ y \in \mathbb{R}^{n+1} : |y_{n+1}| < \lambda \varphi\left(\frac{|y'|}{\lambda}\right) \right\} \cap \left\{ y \in \mathbb{R}^{n+1} : |y_{n+1}| < \frac{\varepsilon_0}{8}(1 + |y'|) \right\}. \quad (18)$$

Let F_ε and v_ε be as in Proposition 3. Note that $v_\varepsilon(x') \geq \frac{\varepsilon}{4}(1 + |x'|)$ for all $x' \in \mathbb{R}^n$. Accordingly, (18) gives that

$$E_\star \subseteq F_{\varepsilon_0/2}. \quad (19)$$

Define now

$$\varepsilon_\star := \inf \left\{ \varepsilon > 0 : E_\star \subseteq F_\varepsilon \right\}.$$

We clearly have that $\varepsilon_\star \leq \varepsilon_0/2$, thanks to (19). We claim that, in fact,

$$\varepsilon_\star = 0. \quad (20)$$

To check this, we argue by contradiction and suppose that $\varepsilon_\star \in (0, \varepsilon_0/2]$. Of course,

$$E_\star \subseteq F_\varepsilon \quad \text{for all } \varepsilon \geq \varepsilon_\star \quad (21)$$

and

$$E_\star \not\subseteq F_\varepsilon \quad \text{for all } \varepsilon \in (0, \varepsilon_\star). \quad (22)$$

In consequence of (22), there exists a sequence of points $\{x^{(j)}\}$ such that $x^{(j)} \in E_\star \setminus F_{\varepsilon_\star - 1/j}$ for every large $j \in \mathbb{N}$.

We claim that

$$\{x^{(j)}\} \text{ is a bounded sequence.} \quad (23)$$

If not, then by (18), (7), and (8) we would get that

$$\lambda \varphi\left(\frac{|(x^{(j)})'|}{\lambda}\right) \geq |x_{n+1}^{(j)}| \geq v_{\varepsilon_\star - \frac{1}{j}}((x^{(j)})') = \left(\varepsilon_\star - \frac{1}{j}\right) |(x^{(j)})'|,$$

for infinitely many j . Setting $r_j := |(x^{(j)})'|/\lambda$, this yields that

$$\limsup_{r \rightarrow +\infty} \frac{\varphi(r)}{r} \geq \limsup_{j \rightarrow +\infty} \frac{\varphi(r_j)}{r_j} \geq \varepsilon_\star > 0,$$

in contradiction with (4). As a result, (23) holds true.

We infer from (23) that, up to a subsequence, $\{x^{(j)}\}$ converges to some $x_\star \in \mathbb{R}^{n+1}$. Necessarily, $x_\star \in \partial F_{\varepsilon_\star} \cap \partial E_\star$. Since $E_\star \subseteq F_{\varepsilon_\star}$ (by (21)), $\partial F_{\varepsilon_\star}$ is smooth, and E_\star is α -stationary, we conclude that

$$H_\alpha[F_{\varepsilon_\star}](x_\star) \leq 0,$$

in contradiction with (9). Hence, (20) must be true and, therefore, $E_\star \subseteq F_\varepsilon$ for all $\varepsilon > 0$. That is, $E_\star \subseteq \{x \in \mathbb{R}^{n+1} : x_{n+1} = 0\}$, which is clearly impossible. The conclusion of Theorem 2 is thus valid. \square

2.2. Graph-type α -stationary surfaces. In this subsection, we prove Theorem 1 under assumption (6), as specified by the next result.

Theorem 5. *If E is an α -stationary set in \mathbb{R}^{n+1} such that (6) holds true for some continuous function $\varphi : [0, +\infty] \rightarrow (0, +\infty)$ satisfying (4), then E is a half-space.*

Theorem 5 is a consequence of a blow-down argument analogous to the one presented for instance in [24, Lemma 3.1]. The technical details go as follows.

Proof of Theorem 5. Up to a vertical translation, we can suppose that $0 \in \partial E$. Notice that condition (6) continues to hold, for a possibly different function φ still fulfilling (4).

We consider the rescaled set

$$E_R := \frac{E}{R} = \left\{ y \in \mathbb{R}^{n+1} : Ry \in E \right\}, \quad (24)$$

for $R > 0$ large. Notice that E_R is α -stationary, $0 \in \partial E_R$, and, by (6),

$$\left\{ y \in \mathbb{R}^{n+1} : y_{n+1} < -\frac{\varphi(R|y'|)}{R} \right\} \subseteq E_R \subseteq \left\{ y \in \mathbb{R}^{n+1} : y_{n+1} < \frac{\varphi(R|y'|)}{R} \right\}. \quad (25)$$

Note that, under our assumptions on φ , for every $\varepsilon > 0$ there exists a constant $C_\varepsilon > 0$ for which we have

$$\varphi(t) \leq C_\varepsilon + \frac{\varepsilon t}{2} \quad (26)$$

for all $t \geq 0$. Consequently, for every $\varepsilon \in (0, 1/4)$ there exists $R_\varepsilon > 0$ such that

$$\{y \in B_1 : y_{n+1} < -\varepsilon\} \subseteq E_R \cap B_1 \subseteq \{y \in B_1 : y_{n+1} < \varepsilon\} \quad (27)$$

holds true for all $R \geq R_\varepsilon$.

Let now ε be lower or equal to the parameter ε_0 of [10, Theorem 6.1]. We remark that such result, stated in [10] for minimizers of the α -perimeter, is also valid for α -stationary sets satisfying (27), as revealed by a careful inspection of its proof—this fact has also been observed in [4] (see also the forthcoming Remark 6 for a link with [9]). Therefore, we can employ [10, Theorem 6.1] in our setting and deduce that, for R sufficiently large,

$$\begin{aligned} \partial E_R &\text{ can be written inside the ball } B_{1/2} \\ &\text{ as the graph of a function } u_R : B'_{1/2} \rightarrow \mathbb{R} \text{ satisfying } u_R(0) = 0 \\ &\text{ and } \|u_R\|_{C^{1,\beta}(B'_{1/2})} \leq C, \end{aligned} \quad (28)$$

for some constants $\beta \in (0, 1)$ and $C > 0$ depending only on n and α .

By definition (24), we conclude that ∂E is the graph of the function $u : \mathbb{R}^n \rightarrow \mathbb{R}$ satisfying $u(x') = R u_R(x'/R)$ for all $x' \in B'_{R/4}$. By this and the uniform bound on the $C^{1,\beta}$ norm of u_R , we find that

$$[\nabla u]_{C^\beta(B'_{R/4})} = \frac{[\nabla u_R]_{C^\beta(B'_{1/4})}}{R^\beta} \leq \frac{C}{R^\beta} \quad \text{for all large } R.$$

Hence, ∇u is constant in \mathbb{R}^n and E is a half-space. \square

Remark 6. We observe that (28) can be also obtained as a consequence of Theorem 2.7 in [9]. Indeed, recalling (4), given $\varepsilon > 0$, let $M_\varepsilon > 0$ be such that

$$\frac{\varphi(r)}{r} \leq \varepsilon \quad \text{for all } r \geq M_\varepsilon. \quad (29)$$

Let also $\varphi_R(r) := \varphi(Rr)/R$. We claim that there exists $R_\star > 0$ such that, for $R \geq R_\star$,

$$\text{if } (x', x_{n+1}) \in \mathbb{R}^{n+1}, |x_{n+1}| \leq \varphi_R(|x'|), \text{ and } |x| \geq 1, \text{ then } |x'| \geq 1/2. \quad (30)$$

To prove this, suppose not. Then, recalling (26) (used here with $\varepsilon = 2$),

$$\begin{aligned} 1 \leq |x|^2 &\leq |x'|^2 + |\varphi_R(|x'|)|^2 \leq \frac{1}{4} + \sup_{|y'| \leq 1/2} |\varphi_R(|y'|)|^2 = \frac{1}{4} + \frac{\sup_{|\xi'| \leq R/2} |\varphi(|\xi'|)|^2}{R^2} \\ &\leq \frac{1}{4} + \frac{1}{R^2} \sup_{|\xi'| \leq R/2} (C_2 + |\xi'|)^2 \leq \frac{1}{4} + \frac{1}{R^2} \left(C_2 + \frac{R}{2}\right)^2 \leq \frac{3}{4} \end{aligned}$$

as long as R is sufficiently large. The contradiction above proves (30).

Let also $N_R(x) := |\chi_{E_R}(x) - \chi_{\{x_{n+1} < 0\}}(x)|$. In view of (25), we know that N_R vanishes outside the set $T_R := \{|x_{n+1}| \leq \varphi_R(|x'|)\}$.

Also, by (30), we see that if $x = (x', x_{n+1}) \in T_R \setminus B_1$ then $|x'| \geq 1/2 \geq M_\varepsilon/R$, provided that $R \geq 2M_\varepsilon$, and hence, by (29),

$$|x_{n+1}| \leq \varphi_R(|x'|) = \frac{\varphi(R|x'|)}{R} \leq \varepsilon|x'|.$$

As a consequence,

$$\begin{aligned} \int_{\mathbb{R}^{n+1} \setminus B_1} \frac{N_R(x)}{|x|^{n+s+2}} dx &\leq \int_{T_R \setminus B_1} \frac{dx}{|x|^{n+s+2}} \leq \int_{\{|x'| \geq 1/2\}} \left(\int_{\{|x_{n+1}| \leq \varepsilon|x'|\}} dx_{n+1} \right) \frac{dx}{|x'|^{n+s+2}} \\ &\leq 2\varepsilon \int_{\{|x'| \geq 1/2\}} \frac{dx'}{|x'|^{n+s+1}} \leq C\varepsilon, \end{aligned}$$

for some constant $C > 0$ depending only on n and s . This, together with (27), gives that the assumptions of Theorem 2.7 in [9] are satisfied, from which one obtains (28).

REFERENCES

- [1] L. Ambrosio, G. De Philippis, L. Martinazzi, *Gamma-convergence of nonlocal perimeter functionals*, Manuscripta Math. **134** (2011), no. 3-4, 377–403.
- [2] J. Bourgain, H. Brézis, P. Mironescu, *Another look at Sobolev spaces*. In: J. L. Menaldi, E. Rofman, A. Sulem, A. (eds.) *Optimal Control and Partial Differential Equations*, IOS Press (2001), 439–455.
- [3] C. Bucur, L. Lombardini, E. Valdinoci, *Complete stickiness of nonlocal minimal surfaces for small values of the fractional parameter*, Ann. Inst. H. Poincaré Anal. Non Linéaire, in print.
- [4] X. Cabré, E. Cinti, J. Serra, *Stable s -minimal cones in \mathbb{R}^3 are flat for $s \sim 1$* , arXiv:1710.08722.
- [5] X. Cabré, M. Cozzi, *A gradient estimate for nonlocal minimal graphs*, Duke Math. J., in print.
- [6] X. Cabré, M. M. Fall, J. Solà-Morales, T. Weth, *Curves and surfaces with constant nonlocal mean curvature: Meeting Alexandrov and Delaunay*, J. Reine Angew. Math., in print.
- [7] X. Cabré, M. M. Fall, T. Weth, *Delaunay hypersurfaces with constant nonlocal mean curvature*, J. Math. Pures Appl. (9) **110** (2018), 32–70.
- [8] X. Cabré, M. M. Fall, T. Weth, *Near-sphere lattices with constant nonlocal mean curvature*, Math. Ann. **370** (2018), no. 3-4, 1513–1569.
- [9] L. Caffarelli, D. De Silva, O. Savin, *Obstacle-type problems for minimal surfaces*, Comm. Partial Differential Equations **41** (2016), no. 8, 1303–1323.
- [10] L. A. Caffarelli, J.-M. Roquejoffre, O. Savin, *Nonlocal minimal surfaces*, Comm. Pure Appl. Math. **63** (2010), no. 9, 1111–1144.
- [11] L. A. Caffarelli, E. Valdinoci, *Regularity properties of nonlocal minimal surfaces via limiting arguments*, Adv. Math. **248** (2013), 843–871.
- [12] A. Cesaroni, S. Dipierro, M. Novaga, E. Valdinoci, *Fattening and nonfattening phenomena for planar nonlocal curvature flows*, Math. Ann., in print.
- [13] E. Cinti, J. Dávila, M. del Pino, *Solutions of the fractional Allen-Cahn equation which are invariant under screw motion*, J. Lond. Math. Soc. (2) **94** (2016), no. 1, 295–313.
- [14] E. Cinti, C. Sinestrari, E. Valdinoci, *Neckpinch singularities in fractional mean curvature flows*, Proc. Amer. Math. Soc. **146** (2018), no. 6, 2637–2646.
- [15] M. Cozzi, A. Farina, L. Lombardini, *Bernstein-Moser-type results for nonlocal minimal graphs*, Comm. Anal. Geom., in print.

- [16] M. Cozzi, A. Figalli, *Regularity theory for local and nonlocal minimal surfaces: an overview*. Nonlocal and nonlinear diffusions and interactions: new methods and directions, 117–158, Lecture Notes in Math., 2186, Fond. CIME/CIME Found. Subser., Springer, Cham, 2017.
- [17] J. Dávila, *On an open question about functions of bounded variation*, Calc. Var. Partial Differential Equations **15** (2002), no. 4, 519–527.
- [18] J. Dávila, M. del Pino, S. Dipierro, E. Valdinoci, *Nonlocal Delaunay surfaces*, Nonlinear Anal. **137** (2016), 357–380.
- [19] J. Dávila, M. del Pino, J. Wei, *Nonlocal s -minimal surfaces and Lawson cones*, J. Differential Geom. **109** (2018), no. 1, 111–175.
- [20] S. Dipierro, A. Figalli, G. Palatucci, E. Valdinoci, *Asymptotics of the s -perimeter as $s \searrow 0$* , Discrete Contin. Dyn. Syst. **33** (2013), no. 7, 2777–2790.
- [21] S. Dipierro, O. Savin, E. Valdinoci, *Boundary behavior of nonlocal minimal surfaces*, J. Funct. Anal. **272** (2017), no. 5, 1791–1851.
- [22] S. Dipierro, E. Valdinoci, *Nonlocal minimal surfaces: interior regularity, quantitative estimates and boundary stickiness*. Recent developments in nonlocal theory, 165–209, De Gruyter, Berlin, 2018.
- [23] A. Farina, E. Valdinoci, *Flatness results for nonlocal minimal cones and subgraphs*, Ann. Sc. Norm. Super. Pisa Cl. Sci. (5), in print.
- [24] A. Figalli, E. Valdinoci, *Regularity and Bernstein-type results for nonlocal minimal surfaces*, J. Reine Angew. Math. **729** (2017), 263–273.
- [25] V. Maz'ya, T. Shaposhnikova, *On the Bourgain, Brezis, and Mironescu theorem concerning limiting embeddings of fractional Sobolev spaces*, J. Funct. Anal. **195** (2002), no. 2, 230–238.

(Matteo Cozzi) DEPARTMENT OF MATHEMATICAL SCIENCES
UNIVERSITY OF BATH
CLAVERTON DOWN, BATH BA2 7AY, UNITED KINGDOM
E-mail address: m.cozzi@bath.ac.uk

(Enrico Valdinoci) DEPARTMENT OF MATHEMATICS AND STATISTICS
UNIVERSITY OF WESTERN AUSTRALIA
35 STIRLING HIGHWAY, WA 6009 CRAWLEY, AUSTRALIA
E-mail address: enrico.valdinoci@uwa.edu.au